

## EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L3	583	(pieter.in. near5 groos.in.) (jan.in. near3 hoogkamp. in.) (josephus.in. near3 vugts.in.) (robert.in. near3 livesey.in.) (johannes.in. near4 franssen.in.) (albert. in. near4 klomp.in.) (johannes.in. near5 vermeulen.in.) (erik.in. near3 loopstra.in.)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/05/21 20:50
L4	13894	(loadlock (load adj lock) load-lock)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/05/21 20:51
L6	3898	(separat\$3 between) with (chamber space environment room) with 4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/05/21 20:52
L7	8	(6 with (pressure vacuum atmosphere)).dlm. and 3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/05/21 20:52
L8	9775628	(transport\$5 transfer\$5 moving move moved moves movement)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/05/21 20:54
L9	940747	8 with (grip\$4 handler arm robot)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/05/21 20:54
L10	2527	6 and 9	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/05/21 20:55

L11	247465	(engag\$3 connect\$3) with (groove protrusion pin hole) with (grip\$4 handler arm robot)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/05/21 20:57
L12	78	9 and 11 and 6	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/05/21 20:58
L13	47	@ad<="20030602" and 12	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/05/21 20:58
L14	6	(tapered) and 13	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/05/21 21:00
L15	0	(9 and 11 and 6 and tapered).dlm.	US-PGPUB; USPAT	OR	ON	2009/05/21 21:01
L16	6	(9 and 11 and 6).dlm.	US-PGPUB; USPAT	OR	ON	2009/05/21 21:01

5/ 21/ 2009 9:02:19 PM

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